

School of Electronic Engineering and Computer Science Queen Mary University of London London, England, E1 4NS

## Adaptive Control of Amplitude Distortion Effects Brecht De Man and Joshua D. Reiss



b.deman@qmul.ac.uk c4dm.eecs.qmul.ac.uk

#### **1** Introduction

- Amount of distortion proportional to input level for most implementations
- Needs careful, manual setting of gain or threshold controls for different input signals and varying levels
- Evaluation of distortion effect that scales the transfer function with moving average of signal level





• Member of adaptive audio effects (A-DAFx) and suitable for use in autonomous mixing systems





### 2 Threshold automation

Transfer function scaled by exponential moving average of RMS level

$$L_{RMS}[n] = \sqrt{(1-\alpha) \cdot x^2[n] + \alpha \cdot L_{RMS}^2[n-1]}$$
  
with x the input signal, and  $\alpha = \exp\left(\frac{-1}{\tau \cdot f_s}\right)$  where  $\tau$  is the charac-

#### **5** Further automation

Make-up gain: RMS level or loudness normalisation to compensate for trimmed signal peaks

**Anti-aliasing**: upsampling ratio based on Nyquist frequency, type of distortion, signal content, and/or user input

Subband gain: approach certain target power per subband (e.g. automatic exciter)

#### teristic time constant and $f_s$ the sampling rate.



# 3 Threshold automation with lookahead

Transfer function scaled by

$$L_{rms}[n] = \sqrt{\begin{array}{c} (1 - \alpha) \cdot \max(x^2[n], x^2[n + 1], \dots, x^2[n + L]) \\ + \alpha \cdot L_{rms}^2[n - 1] \end{array}}$$

#### **6 Perceptual evaluation**



Clean No distortion applied
Static Static distortion applied
Auto 1 Threshold automation
Auto 2 Threshold automation with lookahead



- Four real-word test signals (vocal, Rhodes piano, bass guitar and drums) with artificial 10 dB boost halfway through fragment
- Perceptual evaluation with N = 9 participants
- Perceived amount of distortion consistent
- No significant difference between Auto 1 and Auto 2 (lookahead)